ABSTRACT OF THE DISCLOSURE

For relative positioning between an agricultural machine and crops on their planting rows arranging a sensor is arranged forwardly of a sensor of a rotor of an agricultural machine and at a distance which is at least equal to or greater than a top radius of trees to be worked with the radius being measured in a planting row direction, the tree top by the sensor to determine a rearward point, a forward point, a center point and a farthest transverse point from the center point of a tree top, and the rotor is adjusted to define a trajectory of the rotor center with respect to the points, whereupon the steps are repeated for each of the trees in the planting row to be worked.